

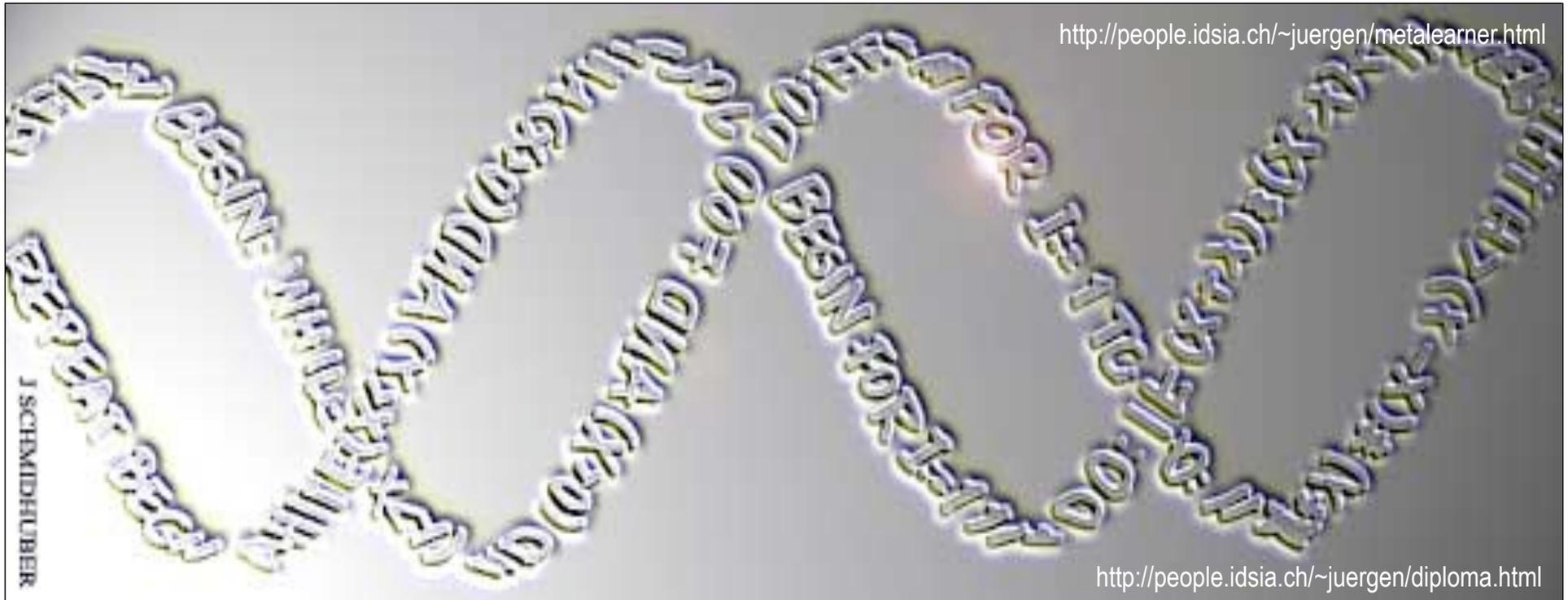
# Learning how to Learn Learning Algorithms

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**NNAISENSE**

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You\_again Shmidhoobuh

<http://people.idsia.ch/~juergen/metalearner.html>



Genetic Programming recursively applied to itself, to obtain Meta-GP and Meta-Meta-GP etc:  
J. Schmidhuber (1987). Evolutionary principles in self-referential learning. On learning how to learn: The meta-meta-...hook. Diploma thesis, TU Munich. 1st concrete design of recursively self-improving AI (RSI), trying to make a first step towards superintelligence. Reinforcement-learn to improve learning algorithm itself, and also the meta-learning algorithm, etc...

“True” Learning to Learn (L2L) is **not** just transfer learning!

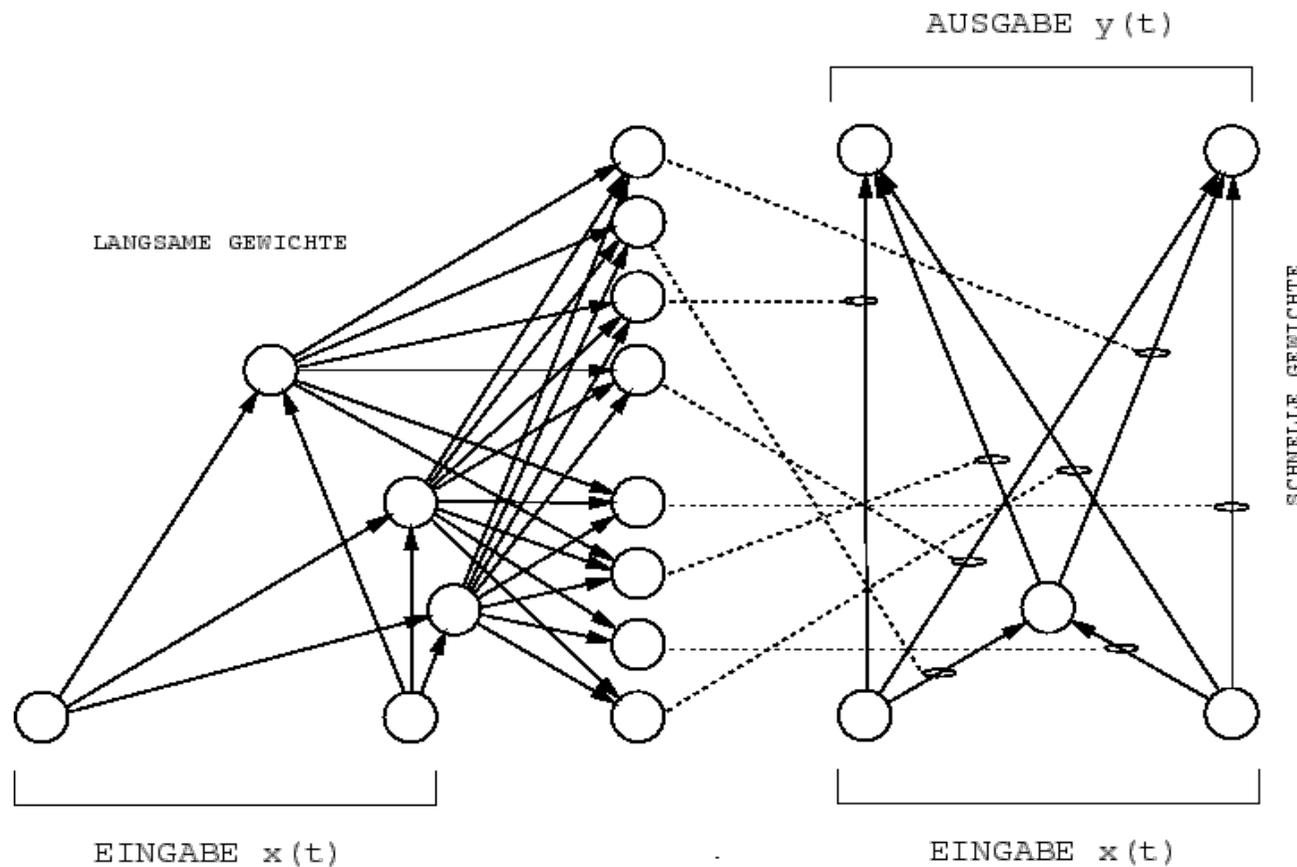
Even a simple feedforward NN can transfer-learn to learn new images faster through pre-training on other image sets

True L2L is **not** just about learning to adjust a few hyper-parameters such as mutation rates in evolution strategies (e.g., Rechenberg & Schwefel, 1960s)

Radical L2L is about encoding the initial learning algorithm in a universal language (e.g., on an RNN), with primitives that allow to modify the code itself in arbitrary computable fashion

Then surround this self-referential, self-modifying code by a recursive framework that ensures that only “useful” self-modifications are executed or survive (RSI)

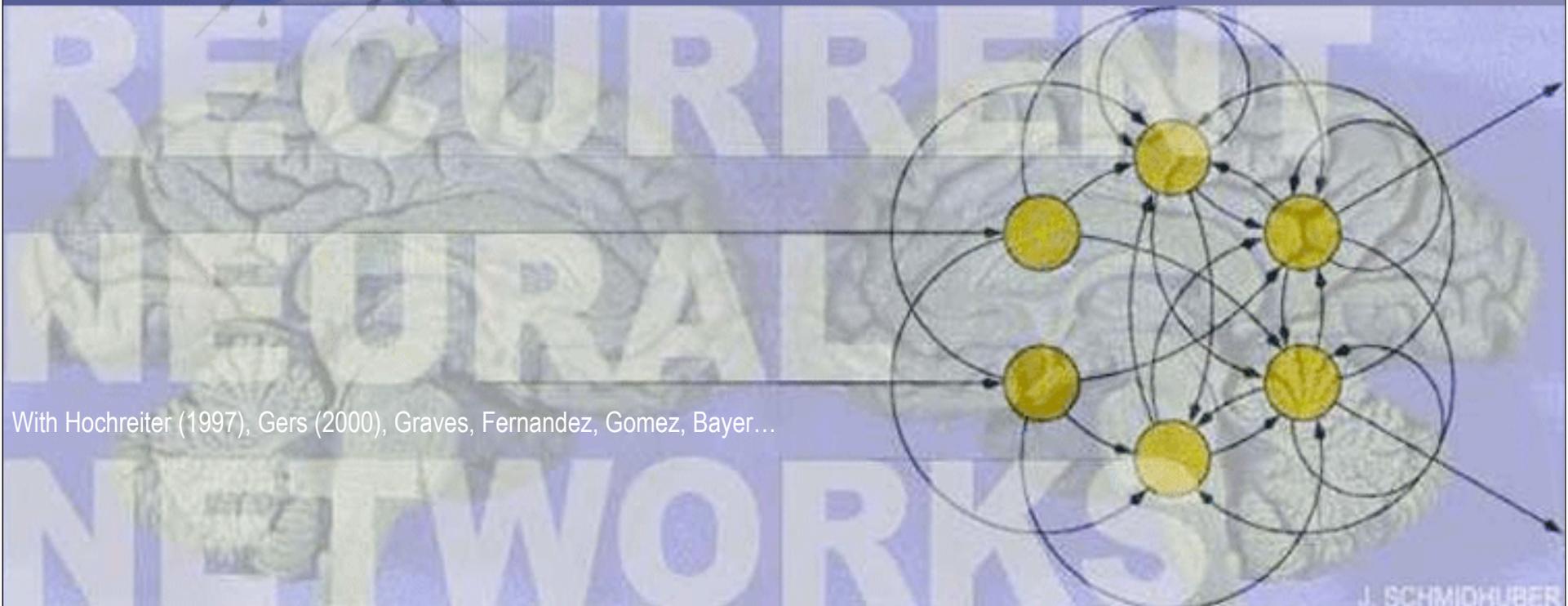
Looks a bit like supervised L2L but is not yet: Separation of Storage and Control for NNs: [End-to-End Differentiable Fast Weights \(Schmidhuber, 1992\)](#) extending v.d. Malsburg's non-differentiable dynamic links (1981)



<http://www.idsia.ch/~juergen/rnn.html>

# LONG SHORT-TERM MEMORY

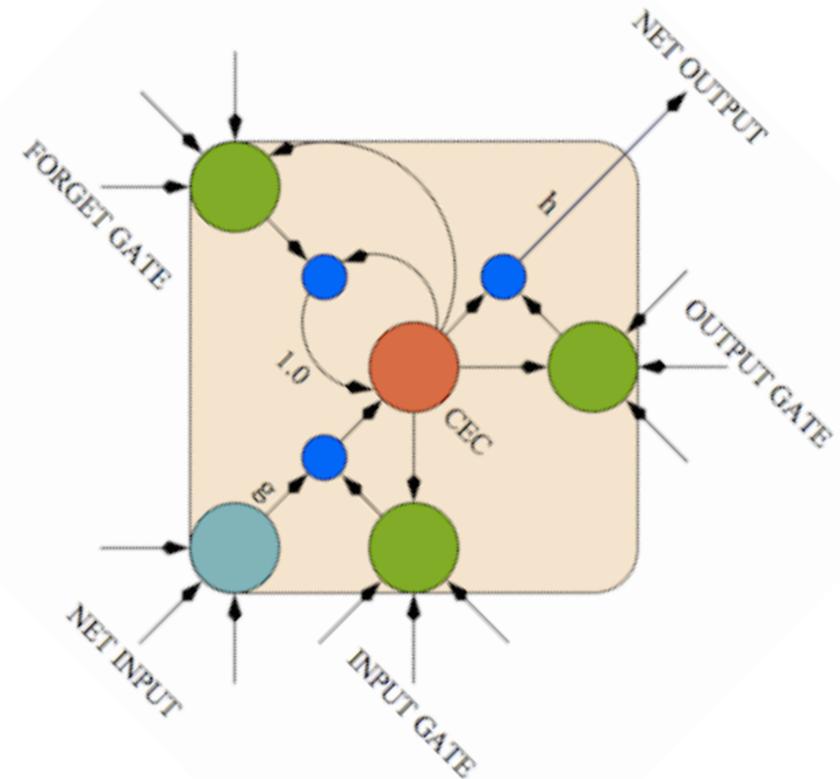
1997-2009. Since 2015 on your phone! Google, Microsoft, IBM, Apple, all use LSTM now



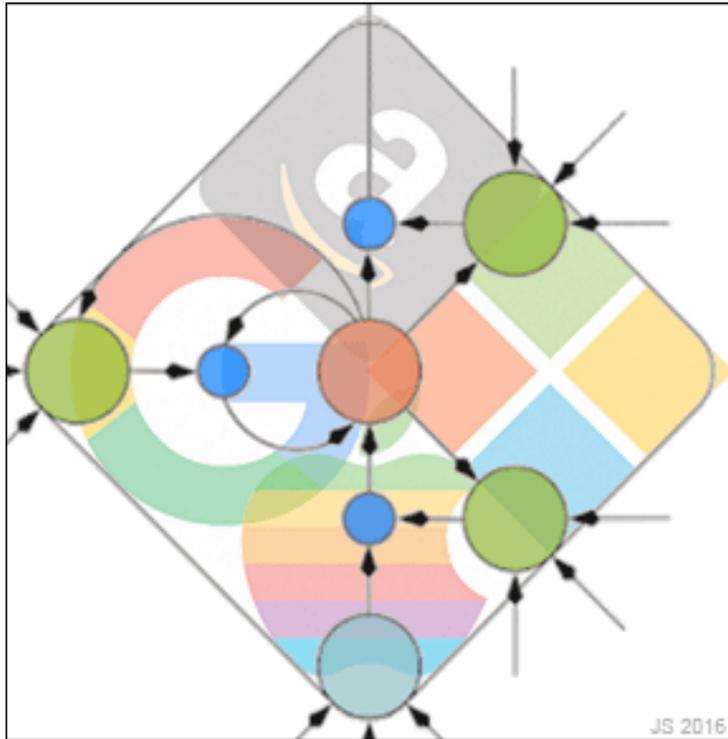
Today's LSTM has fast weights in the forget gates! LSTM shaped by:

Ex-PhD students (TUM & IDSIA)  
Sepp Hochreiter (PhD 1999), Felix Gers (PhD 2001, forget gates for recurrent units), Alex Graves (e.g., CTC, PhD 2008), Daan Wierstra (PhD 2010), Justin Bayer (2009, evolving LSTM-like architectures)

But few would say that LSTM by itself is a metalerner!



LSTM cell



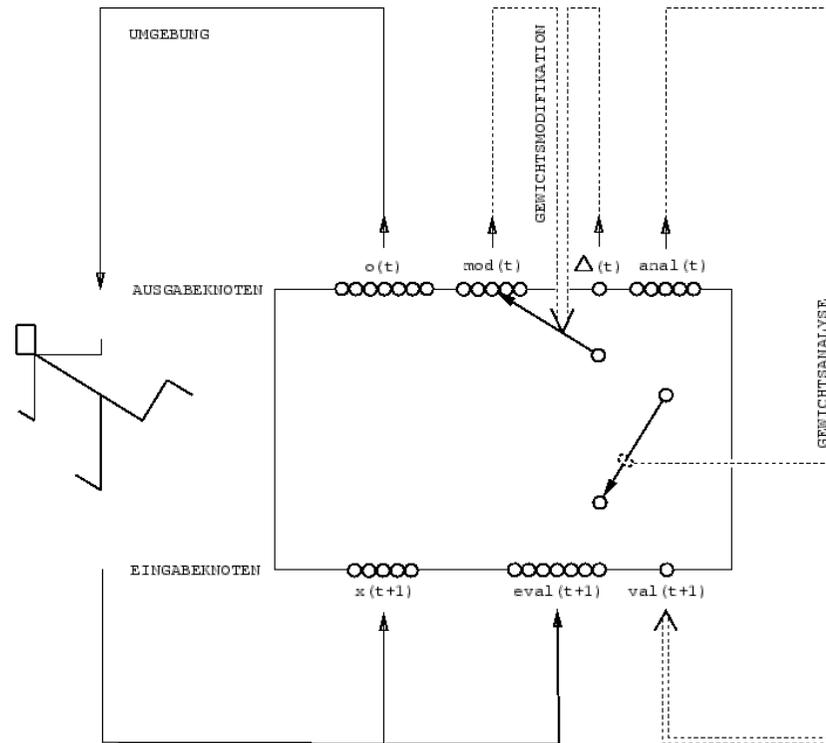
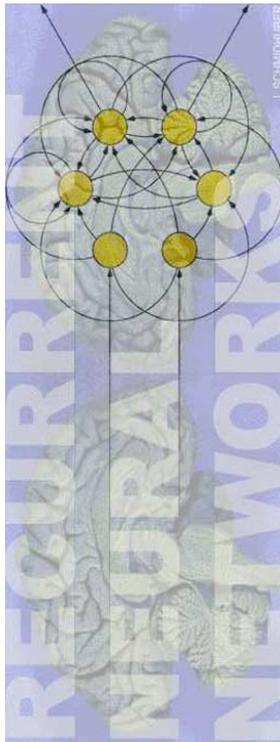
2015: Dramatic improvement of Google's speech recognition through LSTM & CTC (2006), now on 2 billion Android phones. Similar for Microsoft. 2016: LSTM on almost 1 billion Apple iPhones, e.g., Siri. 2016: Google's greatly improved Google Translate uses LSTM; also Amazon's Echo. 2017: Facebook uses LSTM for over 4 billion translations each day

Otherwise this would also be metalearning: Almost 30% of the awesome computational power for inference in all those Google datacenters is used for LSTM (Jouppi et al, 2017); 5% for CNNs.



LSTM / CTC also used by

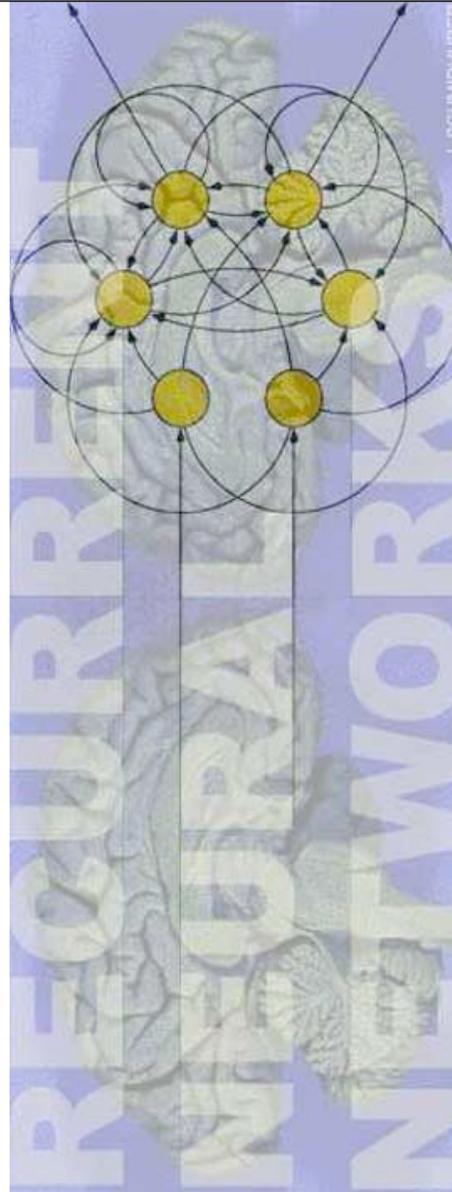




1992-1993:  
 Gradient-based  
 meta-RNNs that can  
 learn to run their own  
 weight change  
 algorithm, e.g.: J.  
 Schmidhuber. A self-  
 referential weight  
 matrix. ICANN 1993.  
 Based on TR at U  
 Colorado, 1992.

An RNN, but no LSTM yet. In 2001, however, Sepp Hochreiter taught a meta-LSTM to learn a learning algorithm for quadratic functions that was faster than backprop

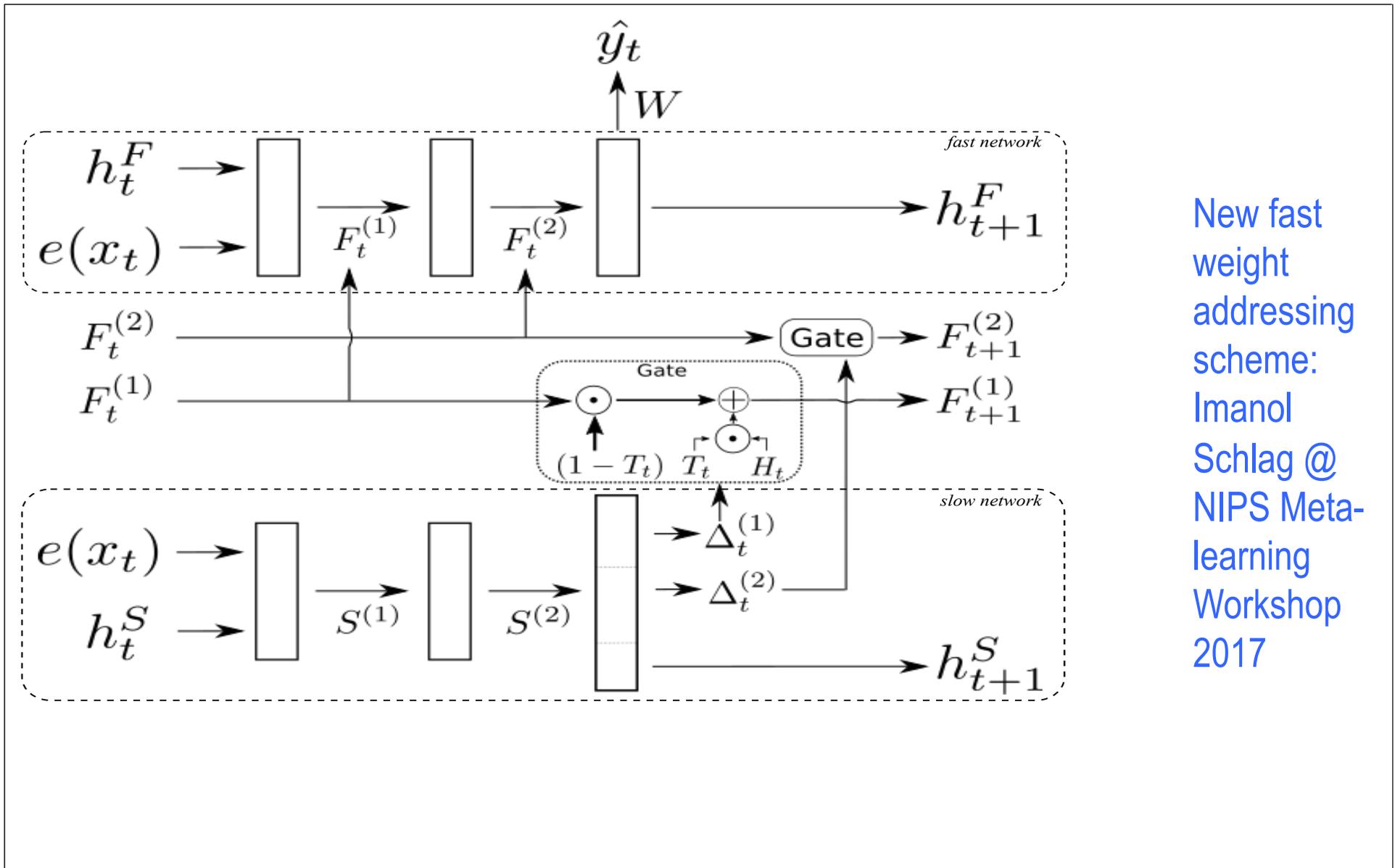
1993: More elegant  
Hebb-inspired  
addressing to go  
from (#hidden) to  
 $(\#hidden)^2$  temporal  
variables: gradient-  
based RNN **learns**  
**to control internal**  
**end-to-end**  
**differentiable**  
**spotlights of**  
**attention for fast**  
**differentiable**  
memory rewrites –  
again **fast weights**



Schmidhuber,  
ICANN 1993:

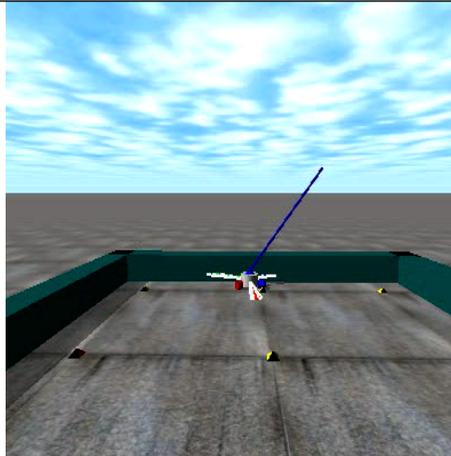
Reducing the ratio  
between learning  
complexity and  
number of time-  
varying variables in  
fully recurrent nets.

Similar NIPS 2016  
paper by Ba et al.  
**See I. Schlag at**  
**NIPS Metalearning**  
**Symposium 2017!**

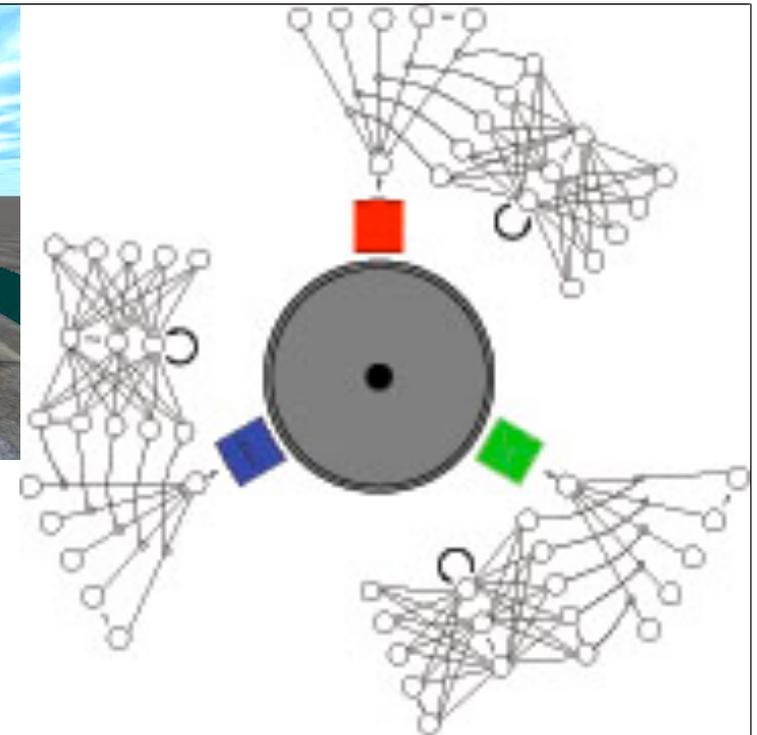
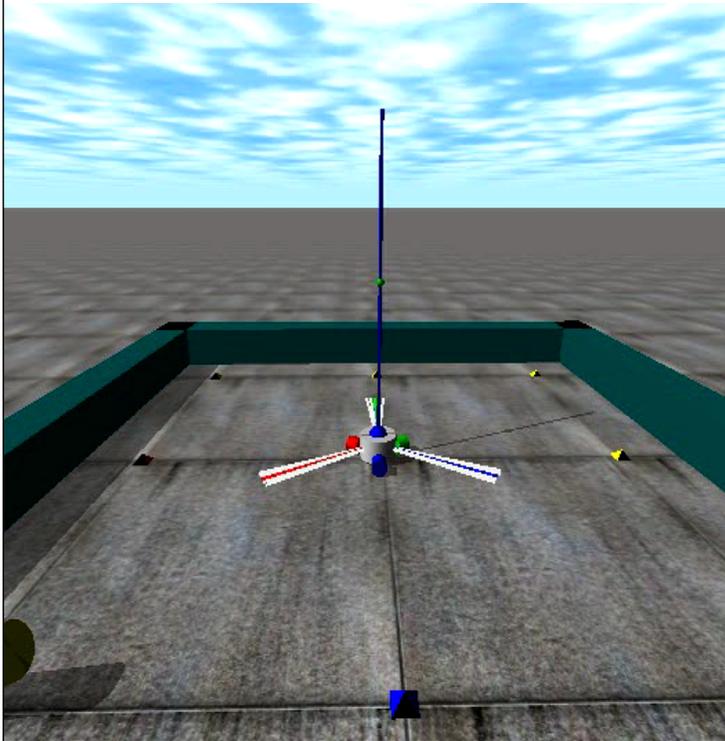


New fast weight addressing scheme:  
 Imanol Schlag @ NIPS Meta-learning Workshop 2017

2005:  
Reinforcement-  
Learning or  
Evolving RNNs  
with Fast Weights



Robot learns to  
balance 1 or 2 poles  
through 3D joint



Gomez & Schmidhuber:  
Co-evolving recurrent  
neurons **learn deep**  
memory POMDPs.  
GECCO 2005

<http://www.idsia.ch/~juergen/evolution.html>

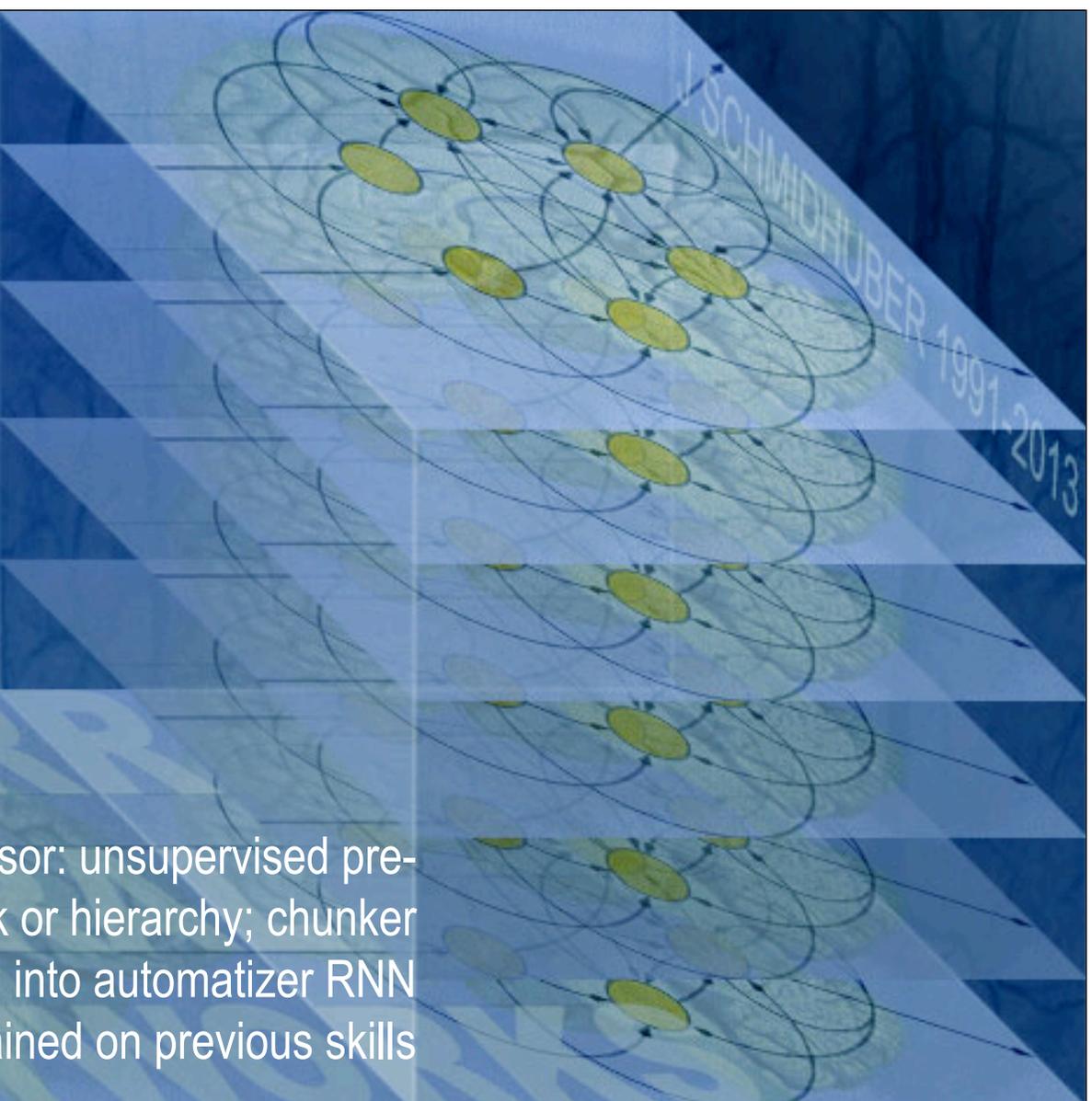
Useful concept of 1991-92:  
compress or collapse or  
distill or clone one NN into  
another (now widely used)

<http://www.idsia.ch/~juergen/firstdeeplearner.html>

Neural history compressor: unsupervised pre-  
training of RNN stack or hierarchy; chunker  
RNN gets compressed into automatizer RNN  
which is also re-trained on previous skills

MY FIRST DEEP  
LEARNER  
1991

J. SCHMIDHUBER 1991-2013



# Success-story algorithm (SSA) for self-modifying code (since 1994)

J. Schmidhuber. On learning how to learn learning strategies.  
TR FKI-198-94, 1994.

$R(t)$ : Reward until time  $t$ . Stack of past check points  $v_1 v_2 v_3 \dots$  with self-mods in between. SSA

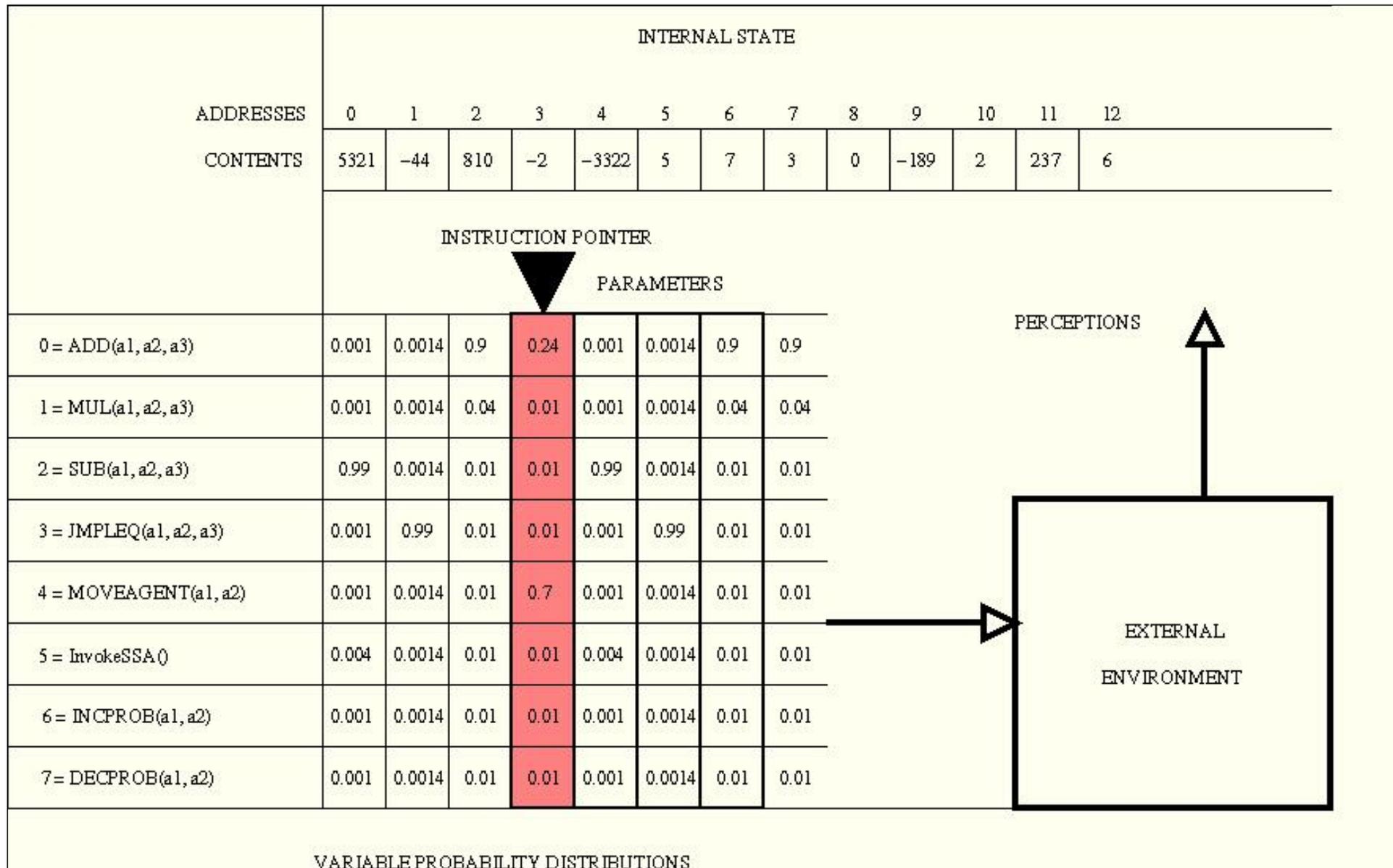
undoes selfmods after  $v_i$  that are not followed by long-term reward acceleration up until  $t$  (now):

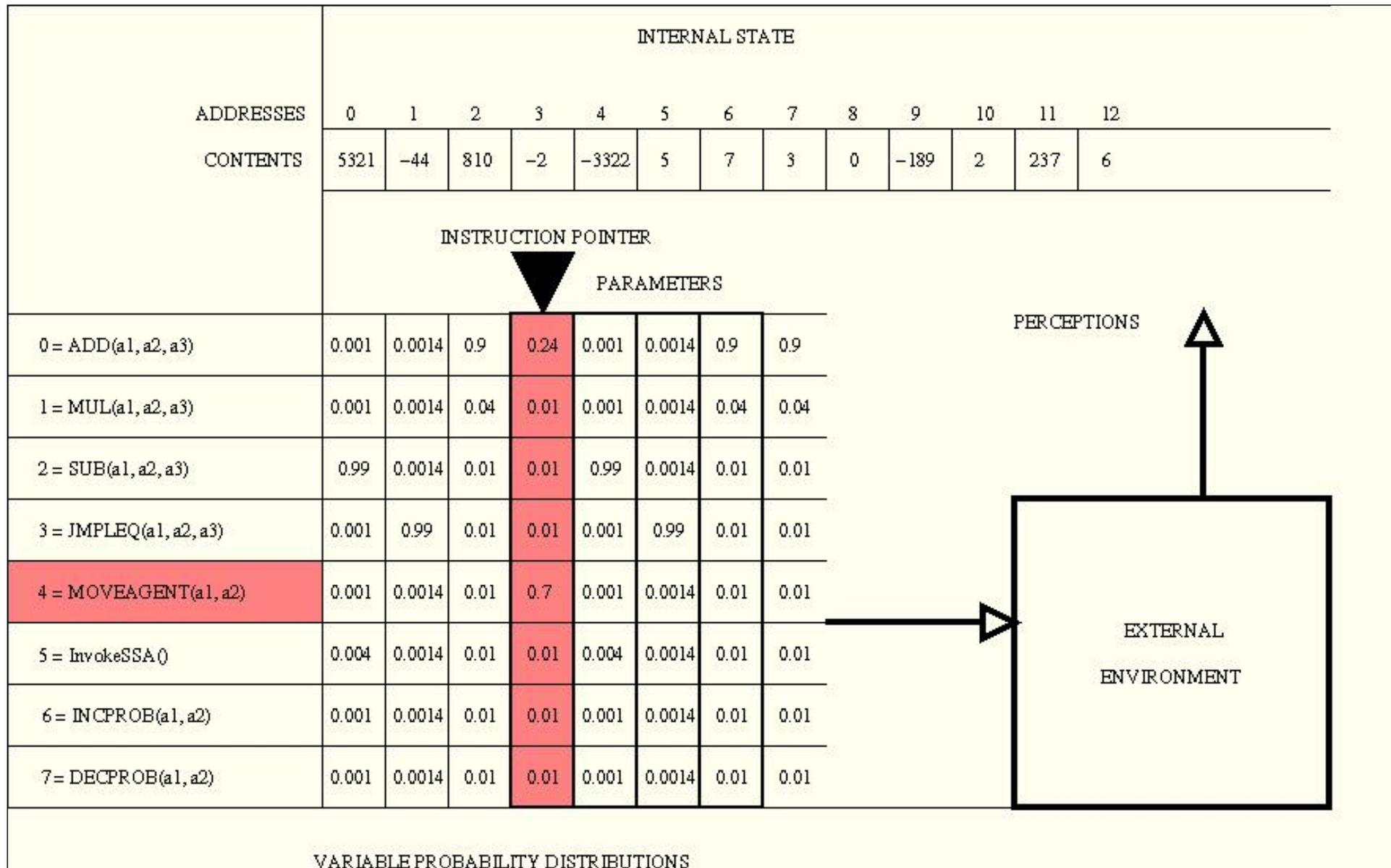


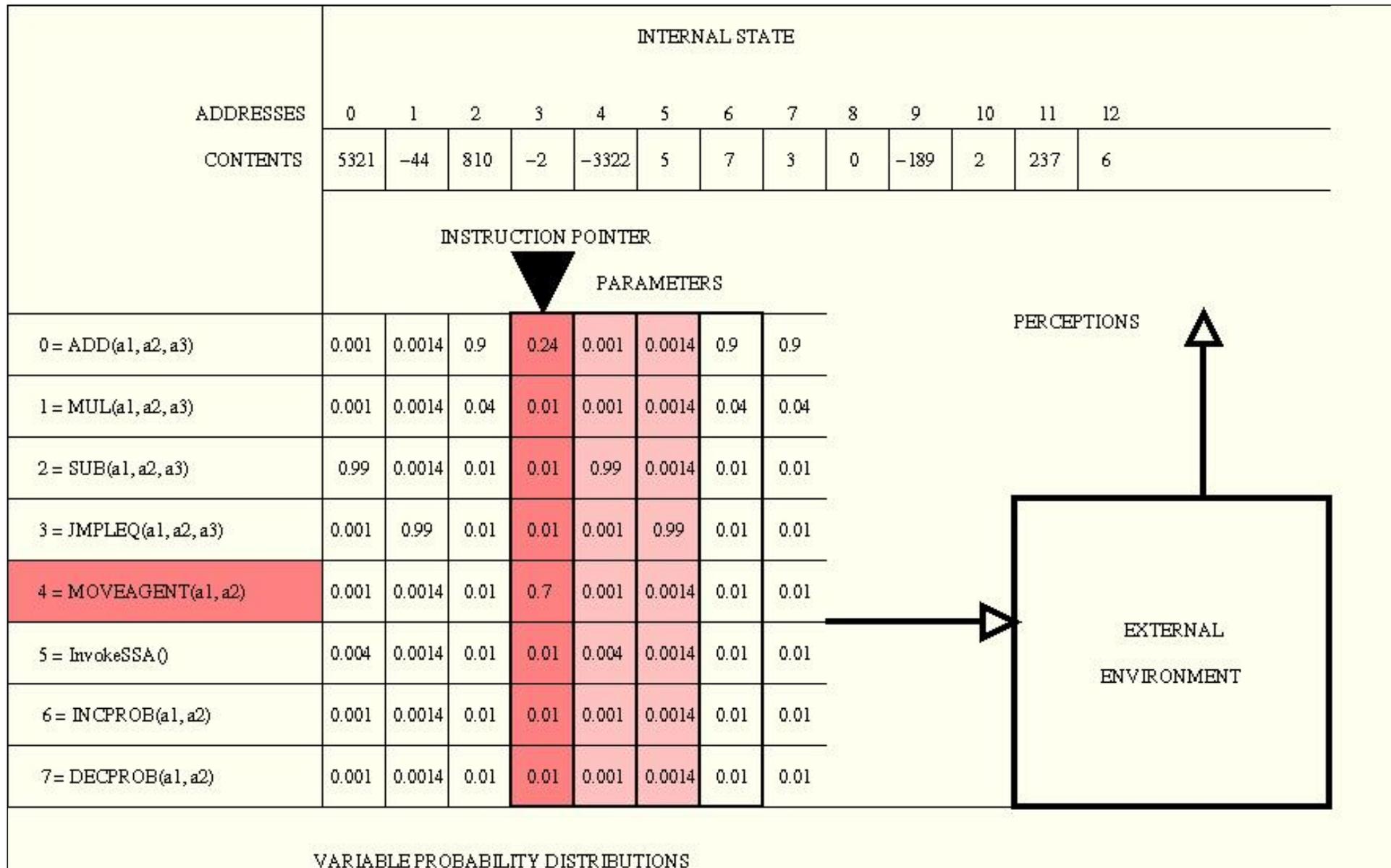
$$R(t)/t <$$

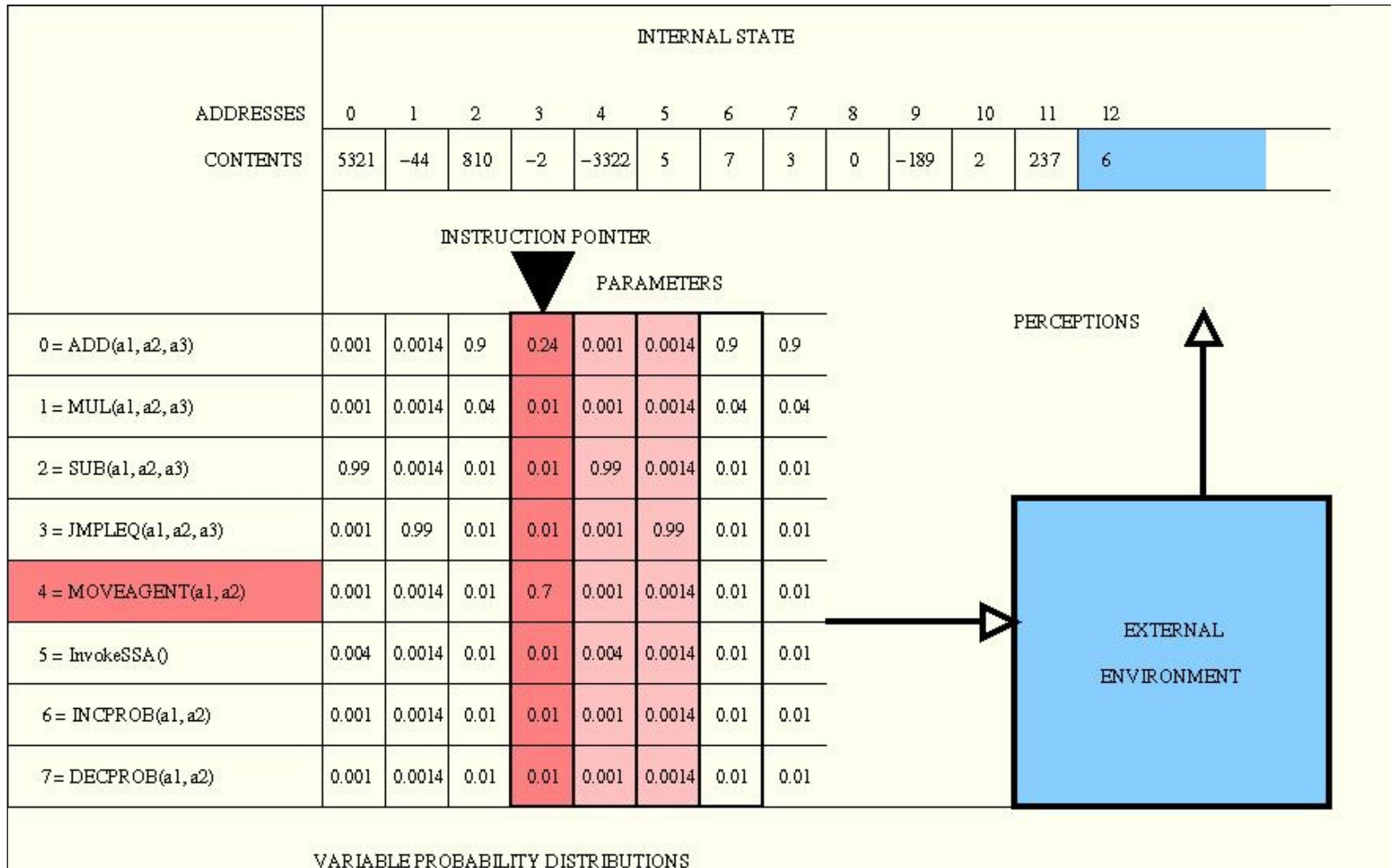
$$[R(t)-R(v_1)] / (t-v_1) <$$

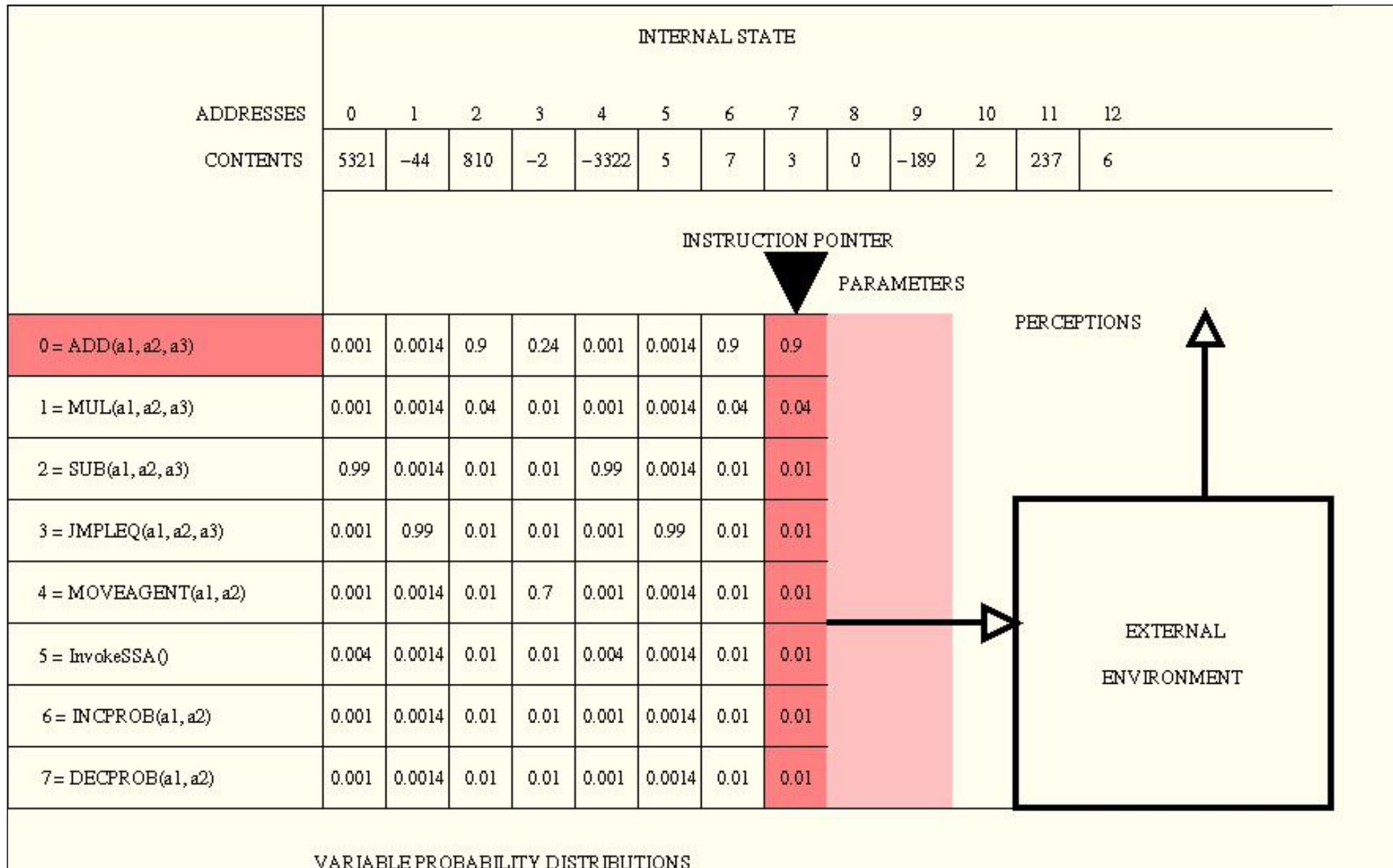
$$[R(t)-R(v_2)] / (t-v_2) < \dots$$

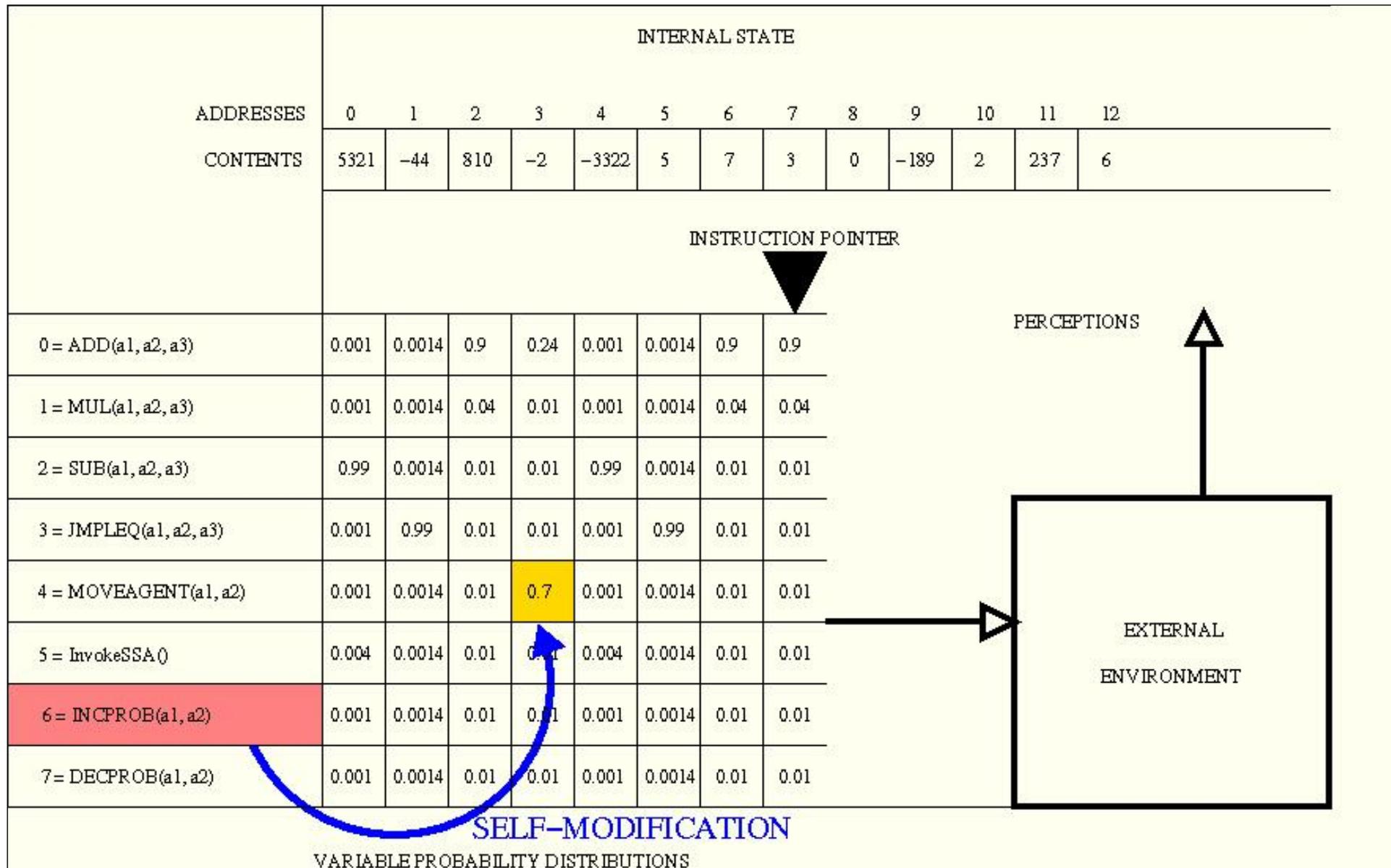


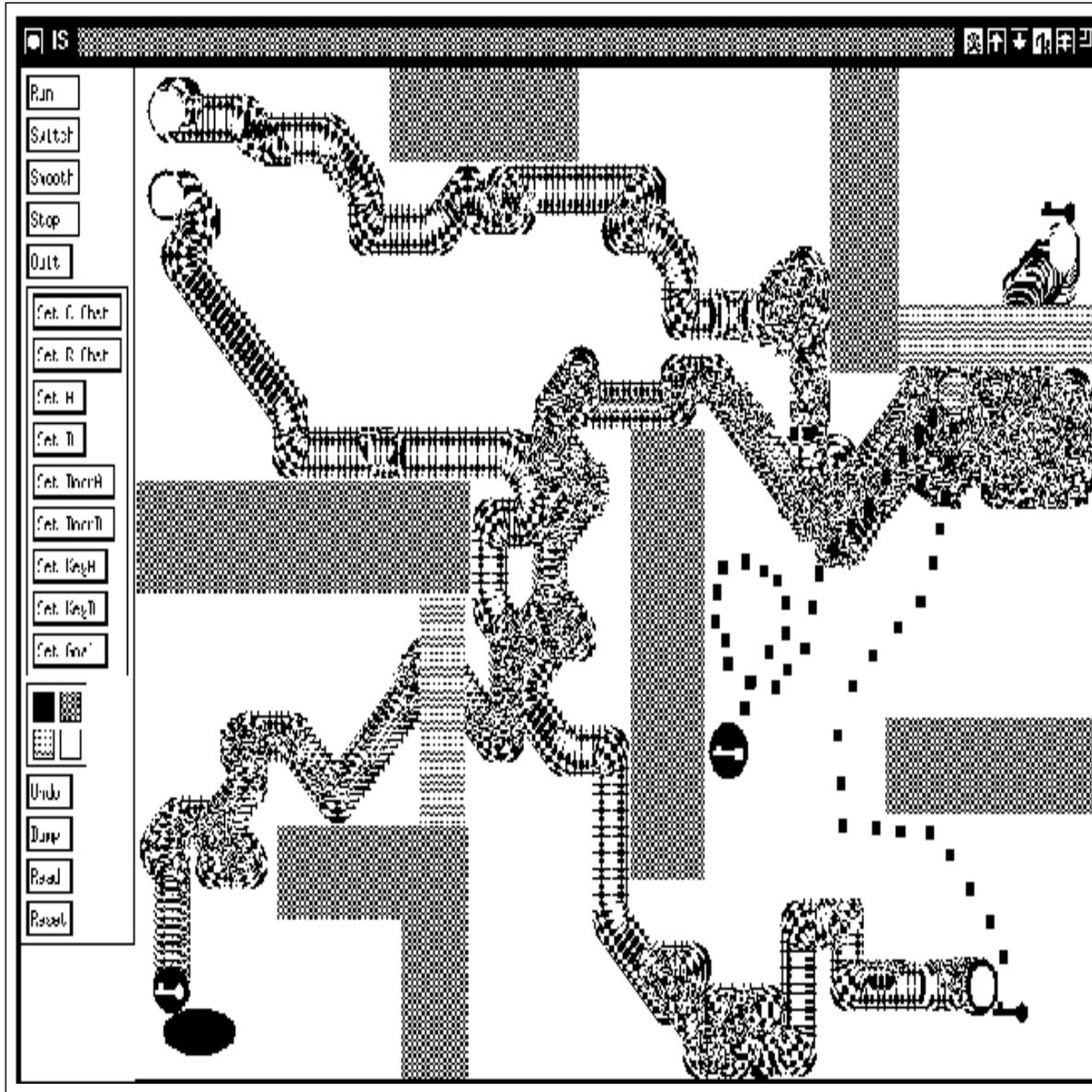












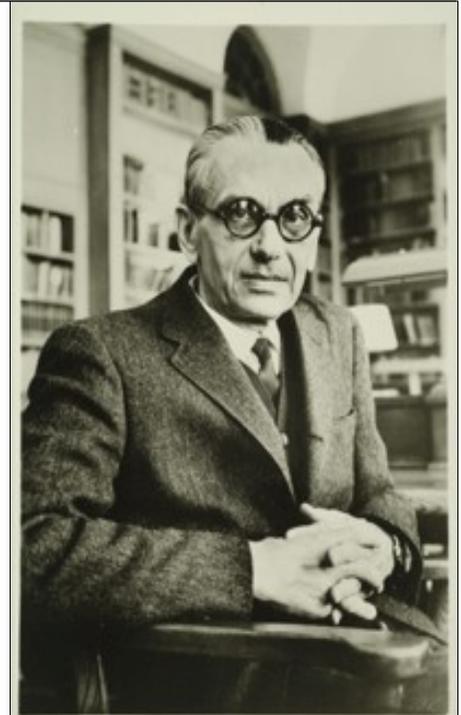
1997: Lifelong meta-RL with self-modifying policies and success-story algorithm: 2

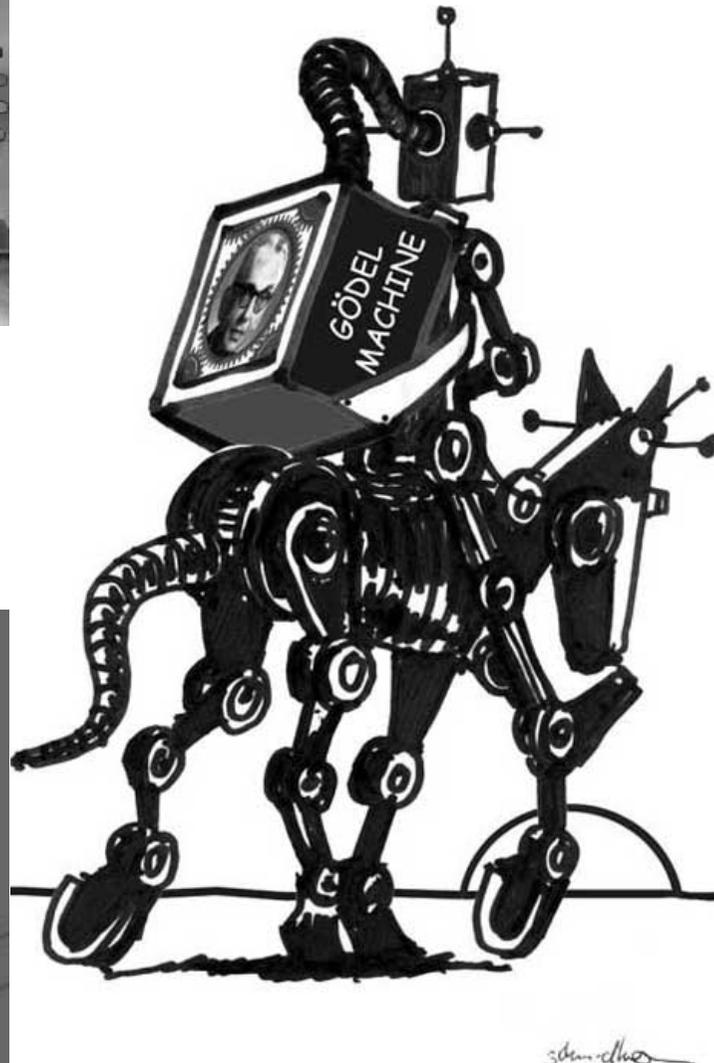
agents, 2 doors, 2 keys. 1st southeast wins 5, the other 3.

Through recursive self-modifications only: from 300,000 steps per trial down to 5,000.

Kurt Gödel, father of theoretical computer science and of AI theory, exhibited the limits of math and computation and AI (1931) by creating a formula that speaks about itself, claiming to be unprovable by a computational theorem prover: either formula is true but unprovable, or math is flawed in an algorithmic sense

Universal problem solver Gödel machine uses self reference trick in a new way



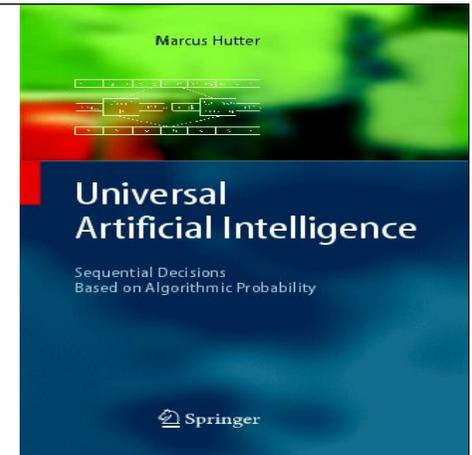


Gödel Machine (2003):  
agent-controlling **program**  
**that speaks about itself**,  
ready to rewrite itself in  
arbitrary fashion once it  
has found a proof that the  
rewrite is **useful**, given a  
user-defined utility function

Theoretically optimal  
self-improver!

Initialize Gödel Machine  
by Marcus Hutter's  
asymptotically fastest  
method for all well-  
defined problems

IDSIA  
2002  
on my  
SNF  
grant



Given  $f: X \rightarrow Y$  and  $x \in X$ , search proofs to find program  $q$  that provably computes  $f(z)$  for all  $z \in X$  within time bound  $t_q(z)$ ; spend most time on  $f(x)$ -computing  $q$  with best current bound

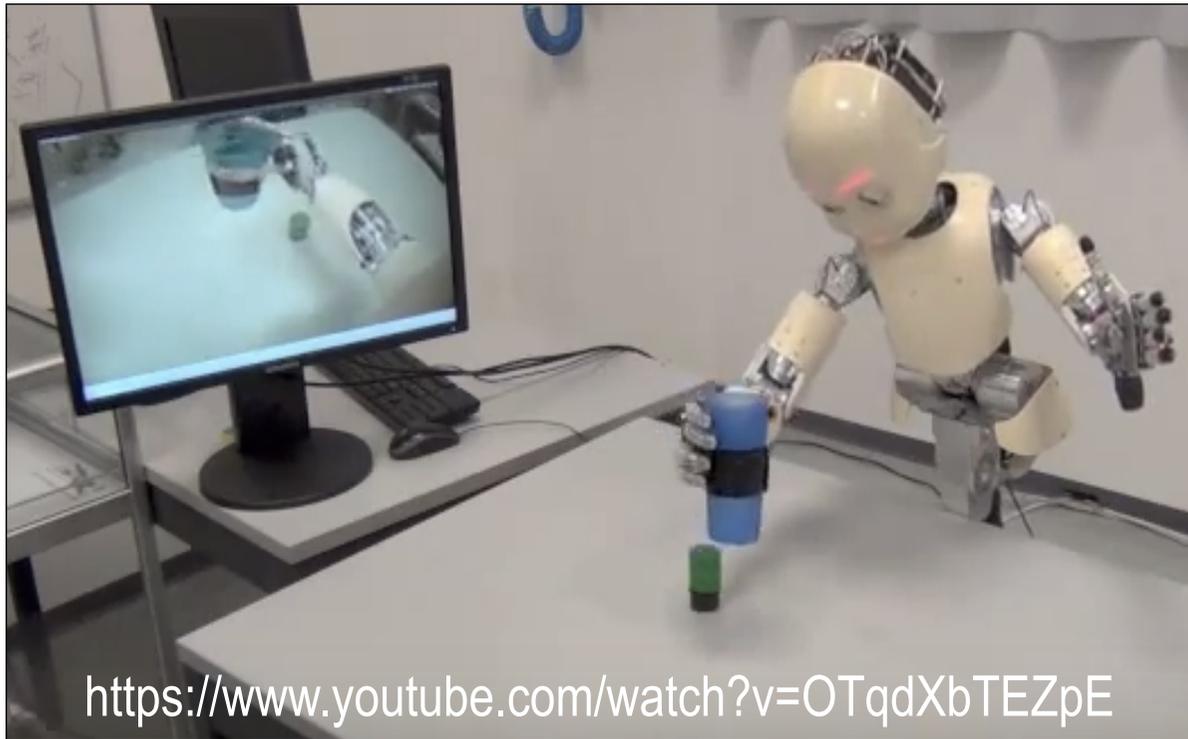
$$n^3 + 10^{1000} = n^3 + O(1)$$

As fast as fastest  $f$ -computer, save for factor  $1 + \varepsilon$  and  $f$ -specific const. independent of  $x$ !

PowerPlay not only solves but also continually invents problems at the borderline between what's known and unknown - training an increasingly general problem solver by continually searching for the simplest still unsolvable problem

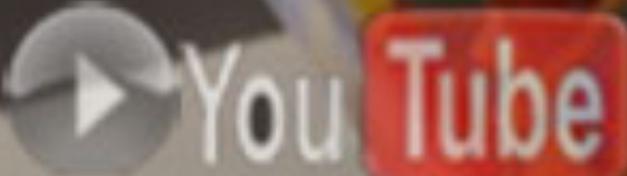
# POWERPLAY





<https://www.youtube.com/watch?v=OTqdXbTEZpE>

Continual curiosity-driven skill acquisition from high-dimensional video inputs for humanoid robots. Kompella, Stollenga, Luciw, Schmidhuber. [Artificial Intelligence, 2015](#)



# AAAI 2013 BEST STUDENT VIDEO AWARD

Mit M Stollenga, K Frank, J Leitner, L Pape, A Foerster, J Koutnik



nnaisense

neural networks-based  
artificial intelligence

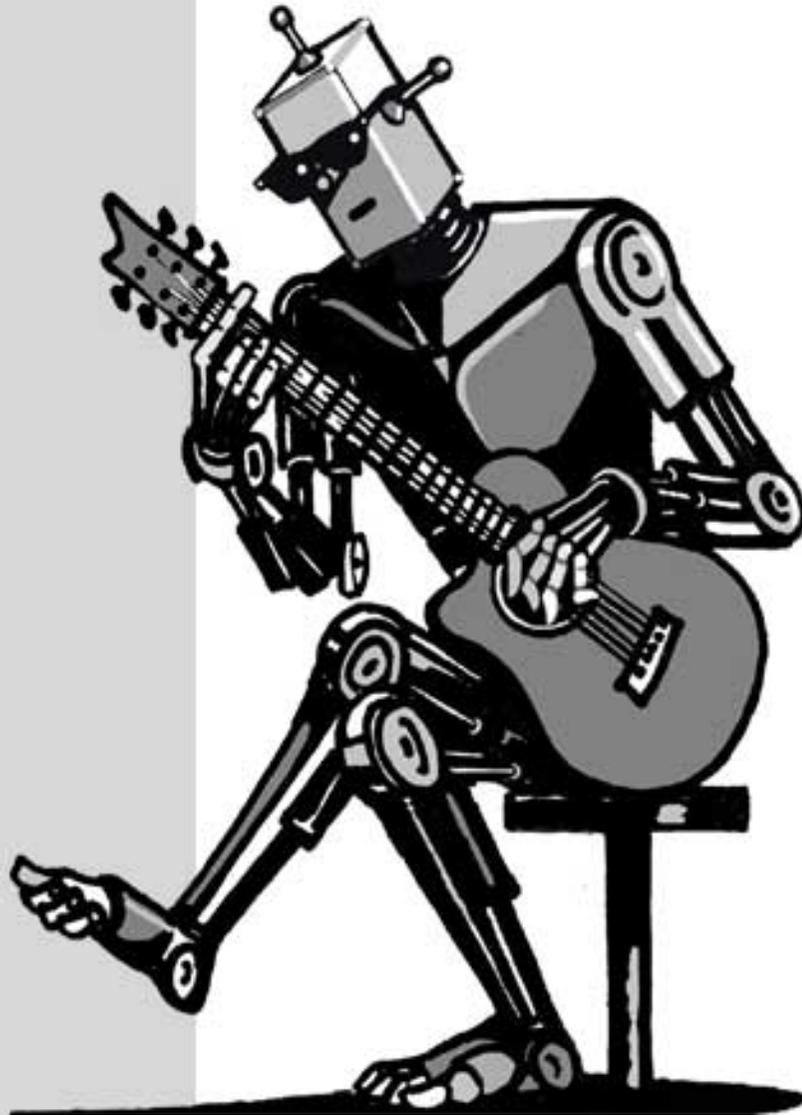
THE DAWN OF AI



<http://people.idsia.ch/~juergen/erc2017.html>

[www.nnaisense.com](http://www.nnaisense.com)

1. Schmidhuber. [Evolutionary principles in self-referential learning, or on learning how to learn: The meta-meta-... hook](#). Diploma thesis, TUM, 1987. (First concrete RSI.)
2. Schmidhuber. [A self-referential weight matrix](#). ICANN 1993. Based on TR CU-CS-627-92, Univ. Colorado, 1992. (Supervised gradient-based RSI.)
3. Schmidhuber. [On learning how to learn learning strategies](#). TR FKI-198-94, 1994. (RL)
4. Schmidhuber and J. Zhao and M. Wiering. [Simple principles of metalearning](#). TR IDSIA-69-96, 1996. (Meta-RL and RSI based on 3.)
5. Schmidhuber, J. Zhao, N. Schraudolph. [Reinforcement learning with self-modifying policies](#). In *Learning to learn*, Kluwer, pages 293-309, 1997. (Meta-RL based on 3.)
6. Schmidhuber, J. Zhao, and M. Wiering. [Shifting inductive bias with success-story algorithm, adaptive Levin search, and incremental self-improvement](#). Machine Learning 28:105-130, 1997. (Partially based on 3.)
7. Schmidhuber. [Gödel machines: Fully Self-Referential Optimal Universal Self-Improvers](#). In *Artificial General Intelligence*, p. 119-226, 2006. (Based on TR of 2003.)
8. T. Schaul and Schmidhuber. [Metalearning](#). Scholarpedia, 5(6):4650, 2010.
9. More under <http://people.idsia.ch/~juergen/metalearner.html>

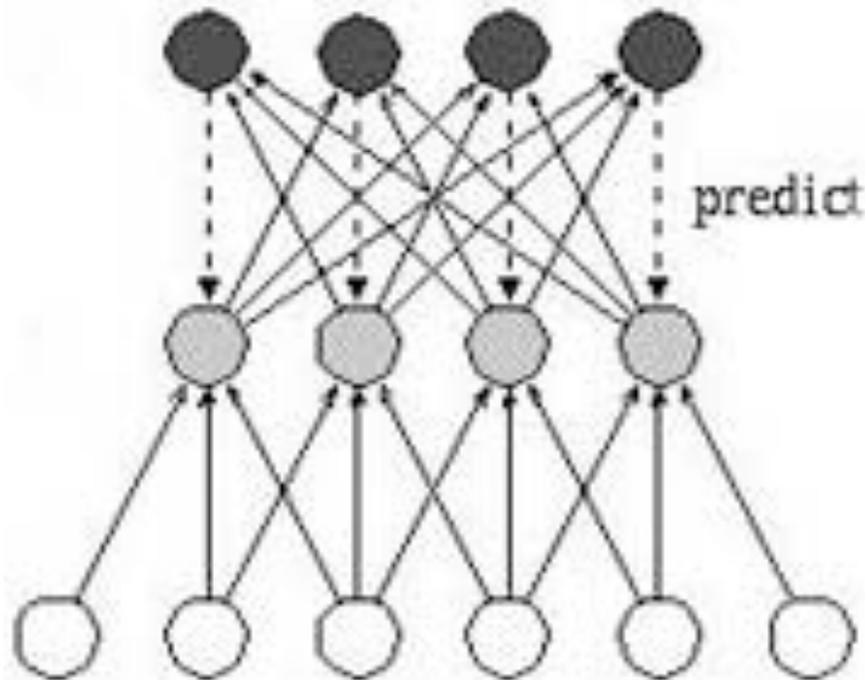


# Learning how to Learn Learning Algorithms: Extra Slides

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1990s: Predictability Minimization: 2 unsupervised nets fight in minimax game to model a given data distribution

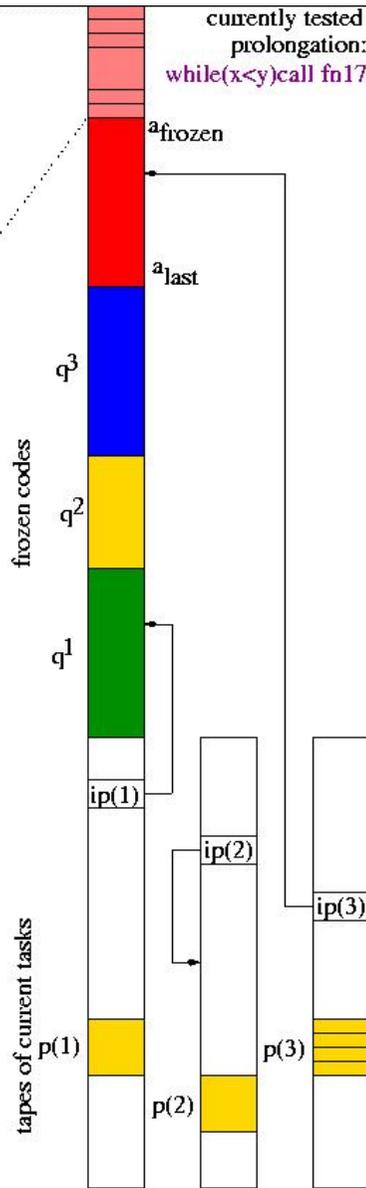
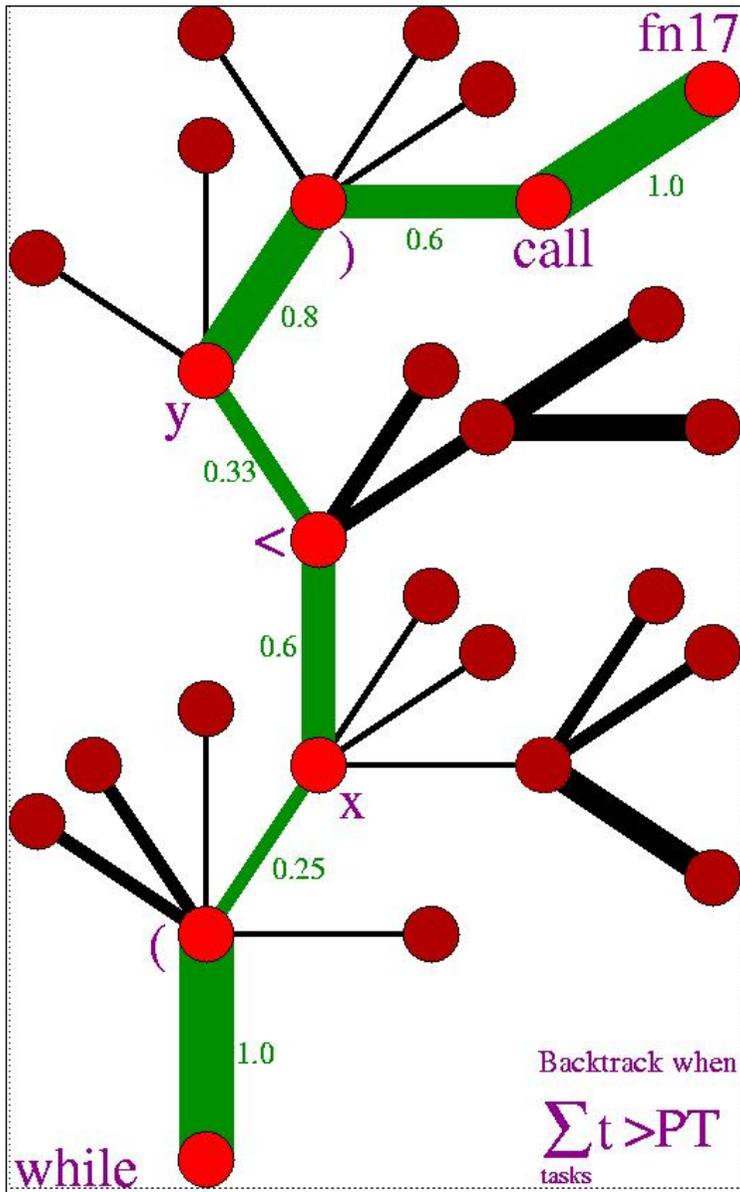


Encoder maximizes objective minimized by predictor. Saddle point = ideal factorial code. Next: similar for Reinforcement Learning!

1997-2002: **What's interesting? Exploring the predictable**

<http://people.idsia.ch/~juergen/interest.html>

Two reinforcement learning adversaries called "left brain" and "right brain" are intrinsically motivated to outwit or surprise the other by proposing an experiment such that the other agrees on the experimental protocol but disagrees on the predicted outcome, which is an internal abstraction of complex spatio-temporal events generated through the execution the self-invented experiment. After execution, the surprised loser pays a reward to the winner in a zero sum game. This motivates the two brain system to focus on the "interesting" things, losing interest in boring aspects of the world that are consistently predictable by both brains, as well as seemingly random aspects of the world that are currently still hard to predict by any brain. This type of artificial curiosity can help to speed up the intake of external reward.

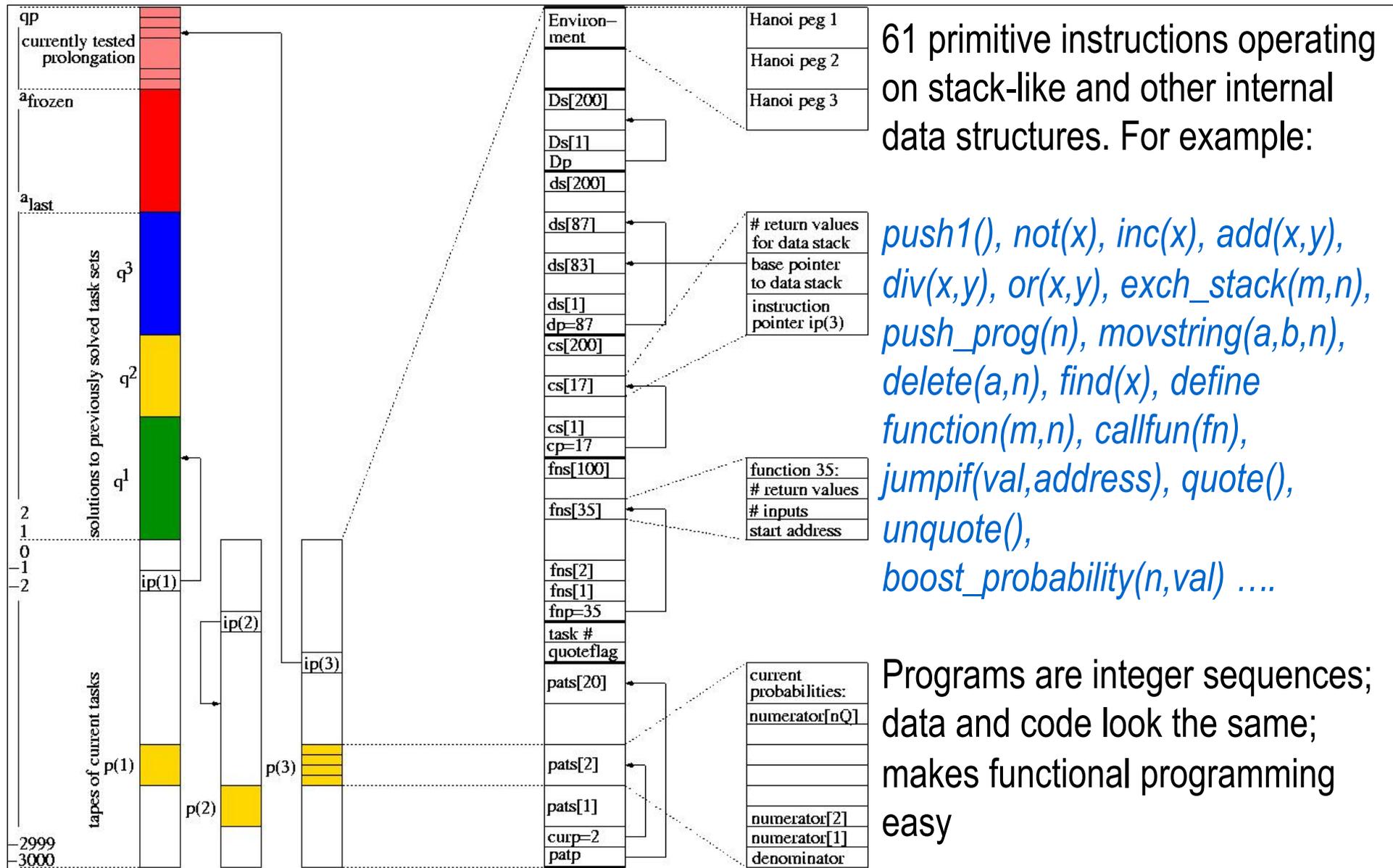


Super-deep program learner:  
Optimal Ordered Problem Solver  
OOPS (Schmidhuber, MLJ, 2004,  
extending Levin's universal  
search, 1973)

Time-optimal incremental search  
and algorithmic transfer learning  
in program space

Branches of search tree are  
program prefixes

Node-oriented backtracking  
restores partially solved task sets  
& modified memory components  
on error or when  $\sum t > PT$



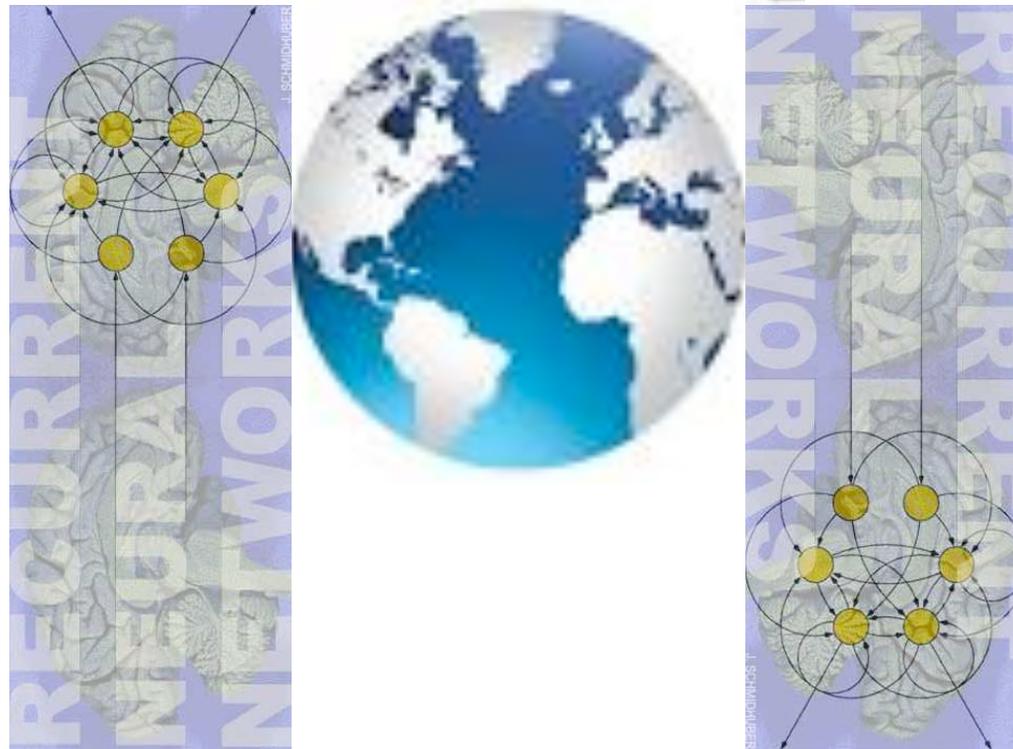
# Towers of Hanoi: incremental solutions

- +1ms,  $n=1$ : (*movdisk*)
- 1 day,  $n=1,2$ : (*c4 c3 cpn c4 by2 c3 by2 exec*)
- 3 days,  $n=1,2,3$ : (*c3 dec boostq defnp c4 calltp c3 c5 calltp endnp*)
- 4 days:  $n=4, n=5, \dots, n=30$ : *by same double-recursive program*
- Profits from 30 earlier context-free language tasks ( $1^n 2^n$ ): *transfer learning*
- 93,994,568,009 prefixes tested
- 345,450,362,522 instructions
- 678,634,413,962 time steps
- longest single run: 33 billion steps (5% of total time)! Much deeper than recent memory-based “deep learners” ...
- top stack size for restoring storage: < 20,000

## What the found **Towers of Hanoi** solver does:

- *(c3 dec boostq defnp c4 calltp c3 c5 calltp endnp)*
- **Prefix increases P of double-recursive procedure:**  
Hanoi(Source,Aux,Dest,n): IF n=0 exit; ELSE BEGIN  
Hanoi(Source,Dest,Aux,n-1); move top disk from Aux to Dest;  
Hanoi(Aux,Source,Dest,n-1); END
- **Prefix boosts** instructions of previously frozen program, which happens to be a previously learned solver of a context-free language ( $1^n 2^n$ ). This rewrites search procedure itself: **Benefits of metalearning!**
- **Prefix probability 0.003; suffix probability  $3 \cdot 10^{-8}$ ; total probability  $9 \cdot 10^{-11}$**
- **Suffix probability without prefix execution:  $4 \cdot 10^{-14}$**
- That is, Hanoi does profit from  $1^n 2^n$  experience and incremental learning (OOPS excels at algorithmic transfer learning): speedup factor 1000

# J.S.: IJCNN 1990, NIPS 1991: Reinforcement Learning with Recurrent Controller & Recurrent World Model



Learning  
and  
planning  
with  
recurrent  
networks

RNNAlssance  
2014-2015

On Learning to  
Think: Algorithmic  
Information  
Theory for Novel  
Combinations of  
Reinforcement  
Learning RNN-  
based Controllers  
(RNNAs) and  
Recurrent Neural  
World Models

<http://arxiv.org/abs/1511.09249>

